

Temperature and emissivity separation
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Plan

- Introduction
- The DEFILTE algorithm
- A simple atmospheric compensation algorithm
- The NEM algorithm for TES
- Application to Camp Dubé data (Blackfly)
- Application to Nicolet data (Blackfly)
- Conclusion

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Introduction

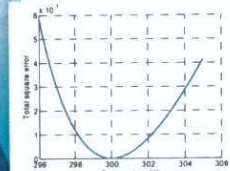
- Camp Dubé was the main site in the Blackfly trial
 - Calibration site was installed
 - Ground truth was acquired
- Westfly experiment
 - Application of TES to image from a uranium mill
 - Airborne data from 1000 m altitude

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DEFILTE algorithm (structure)
 Decoupling by FILTERing of Temperature and Emissivity

Minimum is found using iteration on temperature

Typical error function



```

graph TD
    Init[Initialization] --> Comp[Compute error]
    Comp --> Dec{Error decrease}
    Dec -- Yes --> Inc[T = T + T_step]
    Inc --> Comp
    Dec -- No --> Min{Is T_step at minimum}
    Min -- No --> Adjust[T_step = T_step / 2  
T_step = -T_step]
    Adjust --> Comp
    Min -- Yes --> End[End]
  
```

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DEFILTE
 Error computation

Input

- 1) Temperature (T)
- 2) Measured radiance (R_m)
- 3) Estimated downwelling irradiance (L_d)

```

graph TD
    Input --> CompEm[Compute emissivity at temperature]
    CompEm --> Smooth[Smooths the emissivity]
    Smooth --> CompRad[Compute at-sensor radiance]
    CompRad --> CompErr[Computes error on radiance]
  
```

Variables

- 1) λ - band index
- 2) j - band index after filtering
- 3) G_m - Laser filter coefficient
- 4) ϵ_j - computed emissivity
- 5) $\tilde{\epsilon}_j$ - filtered emissivity
- 6) R_m - Radiance with error due to absorbing
- 7) ϵ_j^2 - Total squared error on radiance

$$\epsilon_n = \frac{R_m - L_d}{B_n(T) - L_d}$$

$$\tilde{\epsilon}_j = \sum_n G_m \epsilon_n$$

$$R_d = \tilde{\epsilon}_j B_j(T) + (1 - \tilde{\epsilon}_j) L_d$$

$$E_j^2 = \sum_n (R_m - R_n)^2 \quad j \Rightarrow n$$

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Advantages of DEFILTE

- Strong against noise
- Strong against error on input parameters
- Availability of tools to estimate algorithm performance depending on operation conditions

Disadvantage of DEFILTE

- Requires the input of downwelling irradiance

Assumption under DEFILTE

- The emissivities are spectrally smooth

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A simple technique for atmospheric compensation Removal of atmospheric effects

- Path radiance and transmittance
- Assumptions for airborne data acquisition
 - Over 10 degrees Planck's law is almost linear
 - Vegetation and water have very high emissivities ~0.99
 - In some bands transmittance is very high
 - Especially true for low altitude airborne data

The pixel having the smoothest equivalent temperature is the air's most representative average temperature

The highest temperature of the warmest vegetation pixel is representative of the pixel's temperature.

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The method

- Radiance: $R = (\epsilon B + (1 - \epsilon)L)\tau + R_p$
- Two pixels having high emissivities: Measured radiance
- Cool Pixel $R_c = B_c$
- Warm Pixel $R_w = B_w\tau + (1 - \tau)B_c$
- Transmittance: $\tau = \frac{R_w - R_c}{B_w - R_c}$
- Path radiance: $R_p = (1 - \tau)R_c$

ϵ : Emissivity - 1
 B : Blackbody function
 L : Downwelling irradiance
 τ : Transmittance
 R_c : Path radiance - $(1 - \tau)B_c$

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Pixel's selection

- Cool pixel
 - Find a pixel having a radiance close to the blackbody shape
 - Same temperature as the average atmospheric layer
 - High emissivity
- High emissivity warm pixel
 - Use of high transmittance bands
 - Compute the standard deviation of the equivalent temperatures
 - Warm pixel
 - Smallest standard deviation
 - Estimate a temperature for the pixel (max of equivalent temperature)

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Computation examples

Transmittance

Path radiance

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The NEM algorithm for TES

- NEM => Normalized emissivity method
 - For vegetation and water $\epsilon \sim 0.99$
 - For minerals things can be different $\epsilon \sim 0.96$
- Compute the equivalent temperatures
- The highest equivalent temperature => the Highest emissivity
- Recompute the emissivities from the estimated temperature

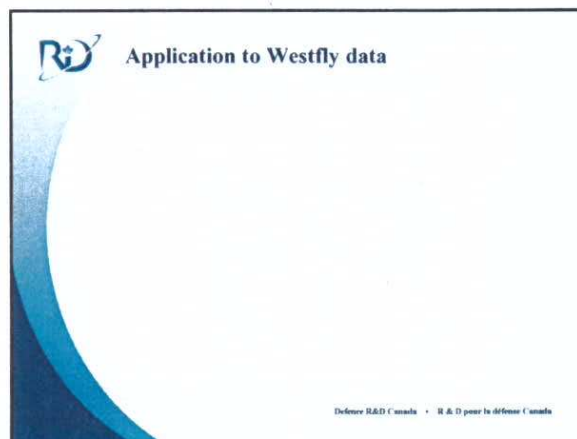
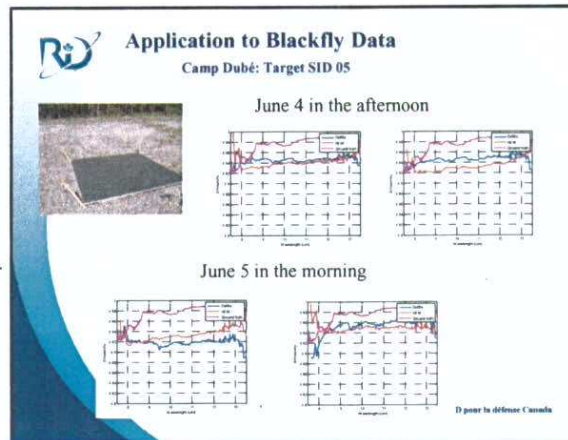
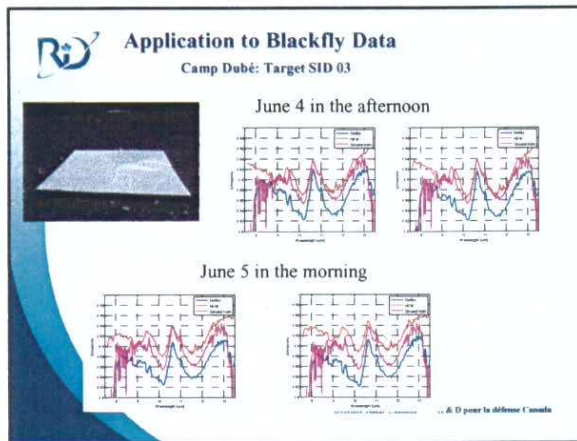
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Application to Blackfly Data

Camp Dubé: Target SID 01

June 4 in the afternoon

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- Conclusion**
- Two algorithms output have been shown (DEFILTE and a simple algorithm)
 - DEFILTE requires the downwelling irradiance
 - Requires calibration targets
 - Difficult to retrieve from other means
 - The simple algorithm makes atmospheric compensation
 - Atmospheric features remain in the emissivity
 - Applicable to acquisition where there is no calibration targets
 - The results are comparable
 - No results for highly reflective targets
 - What are the requirements for identification techniques
 - How clean must be the input emissivity
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